RYAN

CHC

CONCEPTS

openCV

Control theory

SLAM

Path planning

TO-DO

Setup:

* Buy arduino, rasp pi, rpi cam (done)
* Buy breadboard, jumper wires, resistors, sensors (done)
* Buy multimeter, ultrasound sensor (done)
* Buy two of L298N motor driver (done)
* Integration of control and actuator
* Buy f/m jumper wires

Implementation:

* Basic move set
* Light sensor as control
* Ultrasound rangefinder
* Obstacle-avoiding car with random movement

Migrate to github